

**BIS U-6028-048-104-06-ST28 PROFINET**  
**BIS U-6028-048-114-06-ST28 PROFINET**  
**BIS U-6028-048-124-06-ST28 PROFINET**  
**BIS U-6028-048-134-06-ST28 PROFINET**  
**BIS U-6028-048-104-06-ST22 PROFINET**

Technical Description, Operating Manual



**[www.balluff.com](http://www.balluff.com)**

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## 1 User instructions

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## **2** Safety

### **2.1 Intended use**

The BIS U-6028 processor is a component of the BIS U identification system. Within the identification system, it is used to connect to a higher-level controller (PLC, PC); it may only be used in the industrial sector.

This description applies for processors of the following series:

- For operation within the European Community  
BIS U-6028-048-104-06-ST22  
BIS U-6028-048-104-06-ST28
- For operation in the USA, Canada  
BIS U-6028-048-114-06-ST28
- For operation in China  
BIS U-6028-048-124-06-ST28
- For operation in Brazil  
BIS U-6028-048-134-06-ST28

### **2.2 Meaning of the warning notes**



#### **Caution!**

The pictogram used with the word “Caution” warns of a situation that could harm someone's health or damage equipment. Failure to observe these warning notes may result in injury or damage to equipment.

- ▶ Always observe the described measures for preventing this danger.

### **2.3 General safety notes**



#### **Caution!**

This UHF system consists of a processor and antennas according to specifications and may only be operated within the specified countries subject to all applicable national legal regulations and standards.

- ▶ When using the UHF system in the European Community, the provisions in ETSI standard EN 302 208 apply.
- ▶ When using the UHF system in the USA, the directives of FCC, Part 15, apply.
- ▶ When using the UHF system in Canada, the directives of IC, RSS-210 apply.
- ▶ When using the UHF system in Brazil, the directives of ANATEL, 506/2008 and 442/2006 apply.

#### **Installation and startup**

Installation and startup are to be performed by trained technical personnel only.

Any damage resulting from unauthorized manipulation or improper use voids the manufacturer's guarantee and liability claims against the manufacturer. When connecting the processor to an external controller, observe proper selection and polarity of the connection as well as the power supply (see [“Installation” on page 9](#)).

The processor may only be used with approved power supplies (see [“Technical data” on page 12](#)).

## 2 Safety



### Caution!

The antennas of the BIS U identification system transmit ultra-high frequency electromagnetic waves.

IEC 62369 stipulates that personnel may not remain within close range of the UHF antenna for long periods (several hours).

### For operation within the European Community:

When selecting the installation location for the processor, make sure that the minimum distance between the UHF antenna and the workplace is 26 cm.

The radiated power must not exceed the maximum permitted limit values:

- 0.5 watt<sub>ERP</sub> for antennas with an opening angle > 70°,
- 2.0 watt<sub>ERP</sub> for antennas with an opening angle ≤ 70°.

### For operation in the USA, Canada and Brazil:

When selecting the installation location for the processor, make sure that the minimum distance between the UHF antenna and the workplace is 30 cm.

The radiated power must not exceed the permissible limit value of 4 watt<sub>ERP</sub>.



### Note

See the “Basic UHF manual” for more information on minimum/maximum clearance distances and antenna power.

## 2.4 Conformity

### BIS U-6028-048-104-06-ST22, BIS U-6028-048-104-06-ST28



This product was developed and manufactured in accordance with all applicable European Directives. CE conformity has been verified.

### Additional radio interference suppression for BIS U-6028-048-104-06-ST22:

When installing the device, power supply cables need adequate measures for radio interference suppression to ensure compliance to the limits defined in EN 55022. This is achieved by installing 3 pieces of snap ferrite “Würth No. 7427151” close to the device or by means of equivalent measures.

### BIS U-6028-048-114-06-ST28



The product was developed and manufactured in accordance with the directives applicable in the USA and Canada. Conformity has been verified.

### BIS U-6028-048-124-06-ST28



The product was developed and manufactured in accordance with the directives applicable in China. Conformity has been verified.

### BIS U-6028-048-134-06-ST28



The product was developed and manufactured in accordance with the directives applicable in Brazil. Conformity has been verified.



**When using BIS U-6028-048-134-06-ST28 power supply has to be connected via “BIS Power supply FILTER” included in the sales package.**

All approvals and certifications are no longer valid if:

- Components are used that are not part of the BIS U identification system
- Components are used that have not been explicitly approved by Balluff.

### **Operation and testing**

The operator is responsible for ensuring that local safety regulations are observed. If defects and persistent faults occur in the identification system, take it out of service and secure against unauthorized use.

### **3.1 Function principle of identification systems**

The BIS U identification system is classified as a non-contacting system with read and write unction, which not only allows it to detect information programmed permanently in the data carrier, but also to collect and pass on current information.

Main components of BIS U identification systems include:

- Processor
- Antennas
- Data carriers

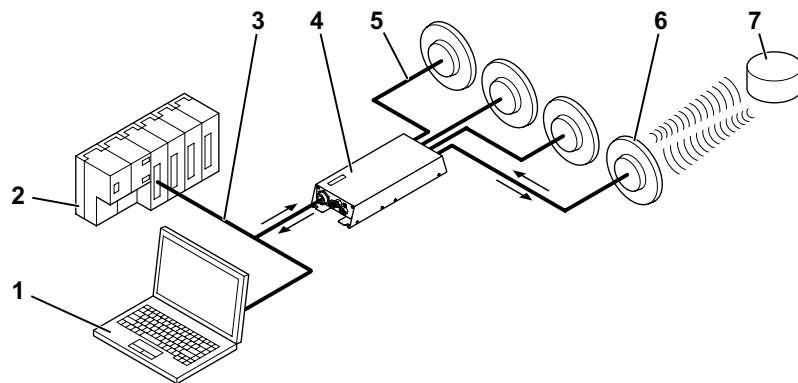


Fig. 1: System overview

- |  |                            |
|--|----------------------------|
| <b>1</b> PC                            | <b>5</b> Antenna cable     |
| <b>2</b> PLC                           | <b>6</b> Antennas (max. 4) |
| <b>3</b> Connection to the host system | <b>7</b> Data carriers     |
| <b>4</b> Processor                     |                            |

The main areas of application are:

- In the production and control of material flow (e.g. in variant-specific processes, workpiece transport in conveying systems, for acquiring safety-relevant data)
- In tool coding and monitoring
- In process equipment organization
- In warehousing for monitoring material movements
- In transporting and conveying
- in waste disposal for quantity-based fee assessment



#### **Note**

See the “Basic UHF manual” for more information on UHF identification systems.

### 3

#### Basic knowledge

##### 3.2 Product description

- UHF-RFID (Operating frequencies see “[Operating frequency and radiated power](#)” on [page 14](#))
- Read/write distance typically up to 6 m depending on ambient conditions and installed system components such as antennas, data carriers, cables, etc.
- Connection option for 4 antennas
- Standard interface: 2 × PROFINET
- Service interface: 1 × RS232
- Rugged metal housing
- Control displays for communication and status
- Data carrier types according to ISO 18000-6 type C or EPCglobal™ Class 1 Generation 2

##### 3.3 Control function

The processor is the link between data carrier and controlling system. It manages two-way data transfer between data carrier and antenna and provides buffer storage.

The processor uses the antenna to write data from the controlling system to the data carrier or reads the data from the data carrier and makes it available to the controlling system.

Host systems may be the following:

- a control computer (e.g. industrial PC),
- a PLC.

##### **Double bit header for asynchronous data transmission:**

If a controller does not synchronously send the data range for updating the input/output buffer, data inconsistencies may occur when sending more than two bytes. Consistency of the sent data can then only be ensured by sending the control bits in the first byte and again in the last bytes of the input/output buffer. By comparing the two bit headers, it can be determined whether the data is fully updated and can be accepted.

This method affects neither the PLC cycle time nor the bus access time. Only one byte in the data buffer for the byte of the second bit header is required instead of using it for data.

##### 3.4 Data integrity

In order to ensure data integrity, the data transfer between the data carrier and processor can be monitored using a CRC-16 data check.

##### 3.5 Bus connection

Processor and controlling system are connected via PROFINET.

The PROFINET IO (decentralized peripheral) is tailored to communication between a controller and decentralized field devices.

PROFINET is a combination of ProfiBus DP and EtherNet in one system, whereby the IO view of ProfiBus is retained. The device model of PROFINET IO is also oriented towards the ProfiBus technology. The characteristics of the IO devices are, however, described by GSD files based on XML (GSDML); project planning/system integration is performed in the same way as for to ProfiBus devices.

In a PROFIBUS network, IO controllers and IO devices are connected to each other using all common network topologies: star, line, ring or tree type topologies are possible.

The BIS U-6028 has a built-in IRT switch with two ports for this purpose. This means that both RT and IRT can be used.



## 4 Installation

### 4.1 Scope of delivery of the processor

Included in the scope of delivery:

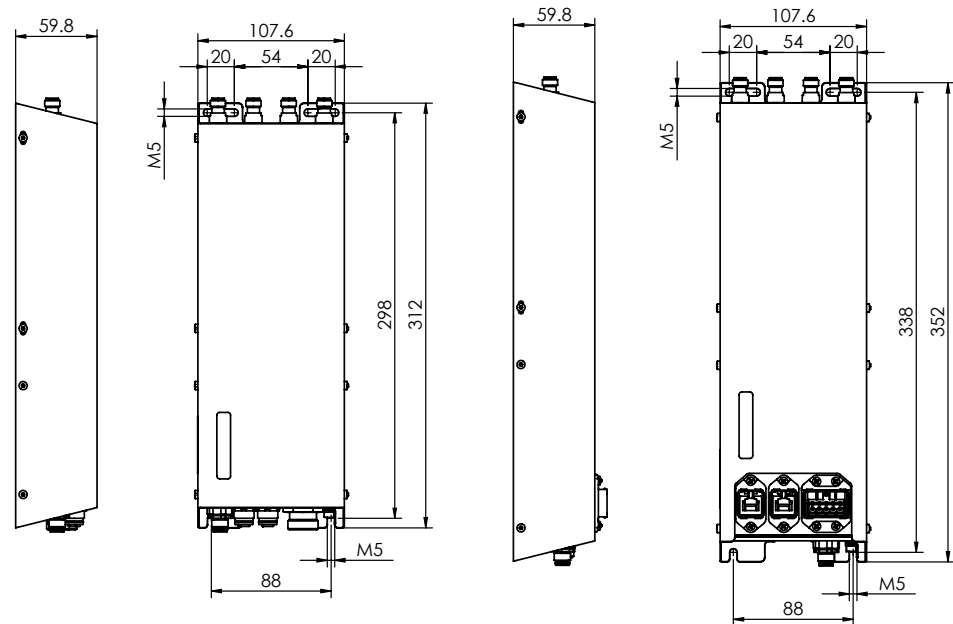
- BIS U-6028
- 5x end caps
- Safety instructions



#### Note

For corresponding technical documents as well as additional information on available software and accessories, see [www.balluff.com](http://www.balluff.com).

### 4.2 Processor installation



BIS U-6028-048-104-06-ST28 PROFINET,  
BIS U-6028-048-114-06-ST28 PROFINET,  
BIS U-6028-048-124-06-ST28 PROFINET,  
BIS U-6028-048-134-06-ST28 PROFINET,

BIS U-6028-048-104-06-ST22

Fig. 2: Installation



#### Caution!

The antennas for the BIS U identification system transmit ultra-high frequency electromagnetic waves!

- The installation position of the processor and antennas must guarantee a safety distance between the antennas and the workplaces of personnel. For safety distances, see [Chapter 2 "Safety" beginning on page 5](#).

The read/write distance can typically be as great as 6 m depending on the ambient conditions and installed system components. See the "Basic UHF manual" for more information on minimum/maximum clearance distances.

- Select a suitable installation position.
- Secure the processor using four M5 screws (strength category 8.8, lightly oiled, tightening torque  $M = 5.2 \text{ Nm}$ ).



#### Note

Optional mounting plates are available for installing the processor (see [Accessories on page 53](#)).

4 Installation

4.3 Interface  
information/  
wiring diagrams

**Note**  
Make the ground connection either directly or using an RC combination to ground.

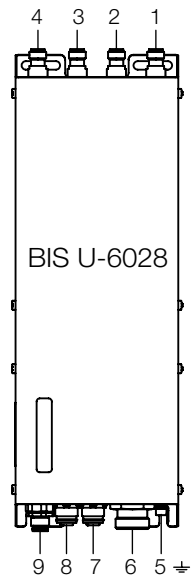
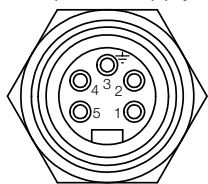


Fig. 3: Electrical connection BIS U-6028-...-ST28

- 1 Antenna port 1
- 2 Antenna port 2
- 3 Antenna port 3
- 4 Antenna port 4
- 5 Function ground FE
- 6 X1 – power supply
- 7 X2 – PROFINET port 2
- 8 X3 – PROFINET port 1
- 9 X4 – service interface RS232

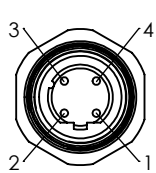
**Note**  
Not all antenna ports 1...4 have to be connected.

X1 - power supply



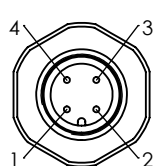
PIN	Function
1	0 V
2	0 V
3	FE
4	+24 V DC
5	+24 V DC

X2/X3 – PROFINET port 1 / port 2



PIN	Function
1	TD+
2	RD+
3	TD-
4	RD-

X4 – service interface RS232



PIN	Function
1	n.c.
2	TxD
3	GND
4	RxD

## 4 Installation



### Note

Make the ground connection either directly or using an RC combination to ground.

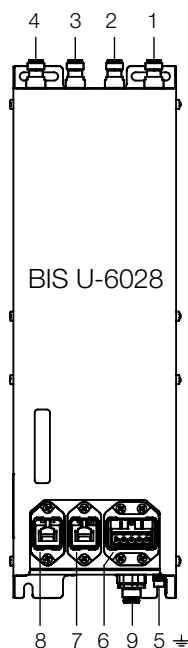


Fig. 4: Electrical connection BIS U-6028-...-ST22

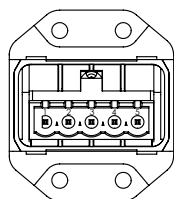
- |                      |                                |
|----------------------|--------------------------------|
| 1 Antenna port 1     | 6 X1 – power supply            |
| 2 Antenna port 2     | 7 X2 – PROFINET port 2         |
| 3 Antenna port 3     | 8 X3 – PROFINET port 1         |
| 4 Antenna port 4     | 9 X4 – service interface RS232 |
| 5 Function ground FE |                                |



### Note

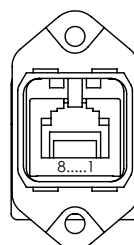
Not all antenna ports 1...4 have to be connected.

X1 - power supply



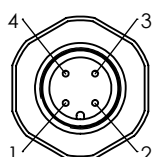
PIN	Function
1	+24 V DC
2	0 V
3	n. c.
4	n. c.
5	FE

X2/X3 – PROFINET port 1 / port 2



PIN	Function
1	TD+
2	TD-
3	RD+
4	n. c.
5	n. c.
6	RD-
7	n. c.
8	n. c.

X4 – service interface RS232



PIN	Function
1	n.c.
2	TxD
3	GND
4	RxD

## 5 Technical data

### Dimensions BIS U-...-ST28

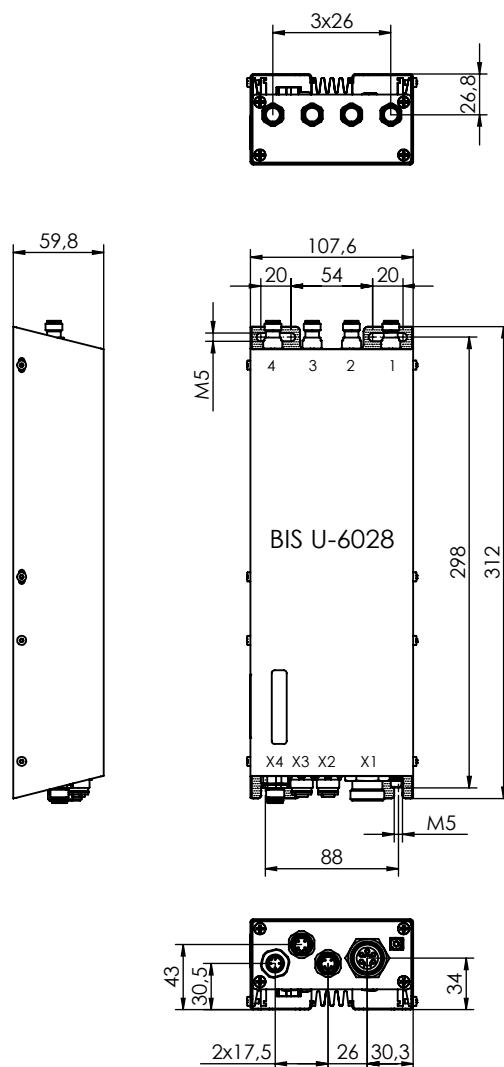


Fig. 5: Dimensions (in mm)

### Mechanical data BIS U-...-ST28

Housing material	Profiled housing and frame made from coated steel
X1 - power supply	V <sub>s</sub> 24 V DC, panel connector 7/8", 5-pin
X2 – PROFINET port 2	M12 panel socket, 4-pin, D-coded
X3 – PROFINET port 1	M12 panel socket, 4-pin, D-coded
X4 – service port	Panel connector M12, 4-pin, A-coded
Antenna ports 1...4	Antenna socket R-TNC
Enclosure rating per IEC 60529	IP 65
Weight	2100 g

## 5 Technical data

### Dimensions BIS U-...-ST22

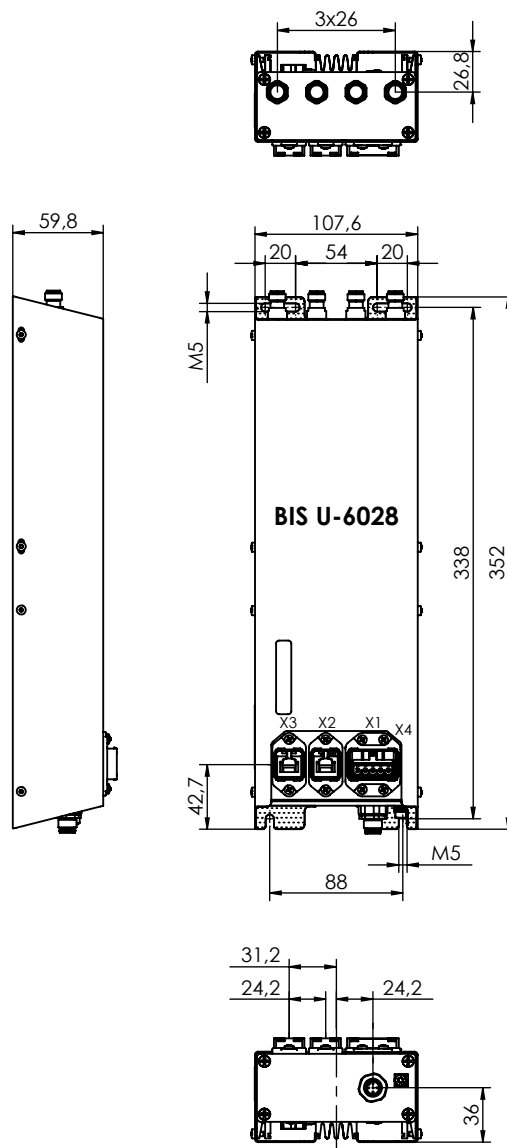


Fig. 6: Dimensions (in mm)

### Mechanical data BIS U-...-ST22

Housing material	Profiled housing and frame made from coated steel
X1 - power supply	V <sub>s</sub> 24 V DC, push-pull power connector (AIDA recommendation), 5-pin
X2 - PROFINET port 2	RJ45 plug (AIDA recommendation)
X3 - PROFINET port 1	RJ45 plug (AIDA recommendation)
X4 - service port	Panel connector M12, 4-pin, A-coded
Antenna ports 1...4	Antenna socket R-TNC
Enclosure rating per IEC 60529	IP 65
Weight	2100 g

## 5 Technical data

### Electrical data

Operating voltage VS	24 V DC $\pm 20\%$
Ripple	$\leq 10\%$
Current draw at 24 V DC	$\leq 1\text{ A}$
X2, X3 – application interfaces	PROFINET
X4 - service interface	RS232
Characteristic impedance of the antenna ports	50 $\Omega$

### Operating frequency and radiated power

#### BIS U-6028-048-104-06-ST22, BIS U-6028-048-104-06-ST28

Operating frequency	865...868 MHz
Maximum permissible radiated power (ERP)	2 watt <sub>ERP</sub>
Number of used channels	4 ETSI channels: 4, 7, 10, 13
Channel selection process	Manual (channel assignment diagram)

#### BIS U-6028-048-114-06-ST28

Operating frequency	902...928 MHz
Maximum permissible radiated power (EIRP)	4 watt <sub>EIRP</sub>
Number of used channels	52
Channel selection process	Automatic (frequency hopping method)

#### BIS U-6028-048-124-06-ST28

Operating frequency	920,5...924,5 MHz
Maximum permissible radiated power (EIRP)	2 watt <sub>EIRP</sub>
Number of used channels	16
Channel selection process	Automatic (frequency hopping method)

#### BIS U-6028-048-134-06-ST28

Operating frequency	915...928 MHz
Maximum permissible radiated power (EIRP)	4 watt <sub>EIRP</sub>
Number of used channels	26
Channel selection process	Automatic (frequency hopping method)

### Operating conditions

Ambient temperature	-20 °C...+55 °C
Storage temperature	-20 °C...+60 °C
EMC (Europe only) IEC 61000-6-2* ETSI EN 301 489 -1 / -3: – Severity level as per EN 61000-4-2/3/4/5/6 – RF emission as per EN 55022	– 2B/3A/DC supply lines 3B, signal lines 4B/2B/3A  – Size 1, Cl. A
Vibration/shock	EN 60068 Part 2-2-6/27/29/32

## 5 Technical data

\* Frequency band exempt from the test: 440 MHz to 465 MHz

This UHF system consists of a processor and antennas as outlined in the specifications and may only be operated in industrial environments and only in the listed countries issuing operating licenses, subject to all applicable national legal regulations and standards.  
(see [Chapter 2 "Safety" beginning on page 5](#)).

### Data carriers

ISO 18000-6	Type C
EPCglobal™	Class 1 Generation 2

### Multi-tagging

Configured EPC length	Maximum number of data carriers (Sum of all active antennas)
96 Bit	25 data carriers
496 Bit	15 data carriers



#### Note

Multitagging operation is supported starting with device software version 1.2 (see part label).

### Function indicators

Operating states	Ready Fault Tag Present Tag Operating LNK1, LNK2 ACT1, ACT2 STA BF	Green LED Red LED Yellow LED Yellow LED Yellow LED Yellow LED Yellow LED Yellow LED
------------------	---	--

## **6** Bus connection

### **6.1 Project planning**

During the project planning of fieldbus devices, a physical device is mapped as a modular system consisting of a head module and multiple data modules. The device data needed for project planning are stored in GSD files (**G**eneral-**S**tation-**D**escription) in GSDML format (**G**eneral **S**tation **D**escription **M**arkup **L**anguage).

#### **GSD file**

The GSDML file for the BIS U-6028 can be downloaded from the BALLUFF website. The data modules of an IO-Link device are represented in the project planning software by slot. The GSDML file provides the possible data modules (inputs or outputs of various data width). For the configuration of an IO-Link device, the appropriate data modules are assigned to a particular slot.

#### **Data modules**

Input and output modules of 8 bytes, 16 bytes, 32 bytes, 64 bytes, 128 bytes and 254 bytes can be configured.

#### **Integration in project planning software**

Project planning is performed, e.g., with the "SIMATIC NCM PC Manager" or "STEP 7" project planning tools.

The following steps are generally necessary for integrating a BIS U-6028 processor:

1. Install the GSDML file of the IO device in the hardware configuration
2. Update catalog
3. Use "Insert object" to add the "BIS U-6028\_RT" IO device.
4. Insert the two modules for inputs and outputs  
(e.g. "RT 32 Byte I" and "RT 32 Byte O" for the "BIS U-6028\_RT" processor)

Additional project planning steps:

5. The name suffix "RT" or "IRT" indicates how the read and write data is exchanged.



#### **Note**

The processor has a two-port IRT switch and is therefore able to pass IRT data packets.

The object properties of the modules can be used to set the start addresses of the input and output data.



#### **Note**

The input and output data can be used to control the BIS U-6028 as described in Chapter "[Device function](#)" on page 27.

### **6.2 Device name and IP address**

6. The object properties of the inserted object "u-6028" can be used to assign the device name, the device number and the IP address.

The processor and the host system communicate via the PROFINET protocol.

This means an IP address and a unique device name are required. The device name and IP address can be saved in the IO device using "Target system > Ethernet > Edit Ethernet device".



#### **Note**

The BIS U-6028 processor is shipped without a device name. In the included GSDML file, the device name "u-6028" is preset.



## 7 Configuring the processor

The configuration of the processor is divided into two parts. One part is the configuration of the BUS parameters. The other is the configuration of the application parameters.

The BUS parameters are configured directly via PROFINET and describe the behavior of the PROFINET interface, see Chapter “[BUS parameters](#)” on page 17

The application parameters are configured via the service interface (RS232) and specify the behavior of the processor with respect to the application, see Chapter “[Application parameters](#)” on page 19

### 7.1 BUS parameters

#### Basic knowledge

#### Schematic structure of the total buffer (process data)

Buffer 1 (for antenna 1 or antenna 3)
Buffer 2 (for antenna 2 or antenna 4)

#### Dynamic mode

If the dynamic mode function (Dynamic) is enabled, the evaluation unit accepts the read/write job from the controlling system and saves it, regardless of whether a data carrier is in the active range of the antenna. If a data carrier enters the active range of the antenna, the stored job is run.

#### Antenna number

If this parameter is activated, the antenna number of the currently selected antenna is displayed in the bit header.

#### Parameter configuration

The configuration is performed during project planning/integration using a project planning software program such as “SIMATIC NCM PC Manager” or “STEP 7”. Alternately, the configuration bytes can be sent directly using the controller.

The parameters for operating the processor are stored in the GSDML file.

#### GSDML file

The GSDML file contains all the device parameters for the processor.

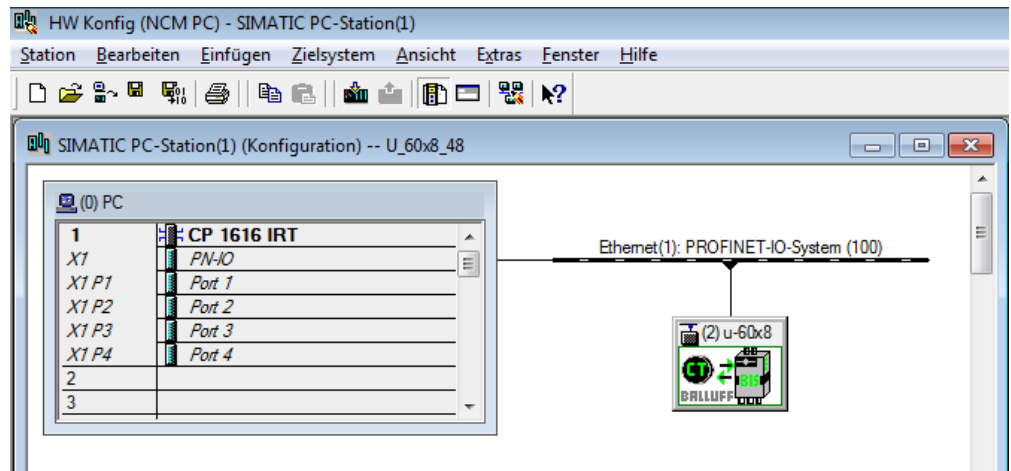
#### Parameter overview

- Dynamic 1/2:  
If dynamic mode is configured, a read/write job can be sent even though no data carrier is present in the active range of the antenna. If a data carrier now arrives at the antenna, the command is immediately executed (saves time).
- Buffer 1:  
This value indicates how many bytes of the entire input and output buffer should be used for buffer 1. The remainder of the input and output buffer is then available for buffer 2.
- ShowAntenna:  
If this is configured, the selected antenna (1 or 3 in buffer 1 or 2 or 4 in buffer 2) in the bit header of the respective buffer is displayed.

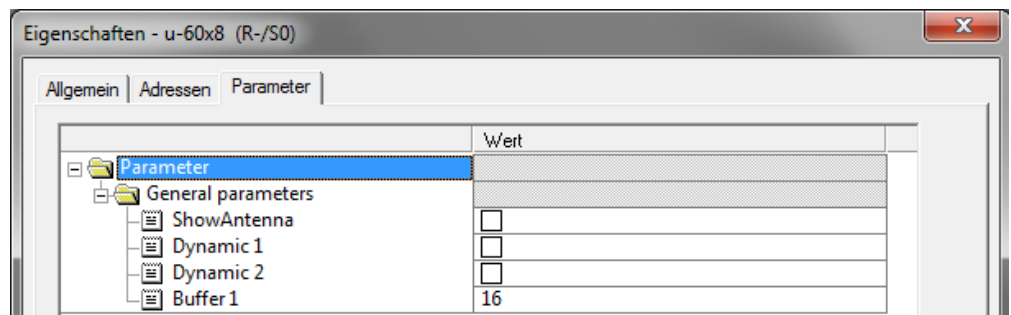
## 7 Configuring the processor

### Parameter configuration during project planning

The project planning software (e.g. "SIMATIC NCM PC Manager" or "STEP 7") can be used to configure the processor in the hardware configuration. To do this, the added IO device is selected and the object properties opened by right-clicking "u-6028" on slot 0:



The "Parameters" tab is used to open the selection window for parameters:



## **7** Configuring the processor

### **7.2 Applications parameters**

#### **Default settings**

The device is preset ex works. The default settings are highlighted for the respective parameters.

Some parameters are fixed and cannot be modified:

#### *Multiplexing:*

The multiplexing sequence and the dwell time in front of each antenna are fixed.

- The sequence in which the antennas are activated is always 1-2-3-4-1-2-....

#### **Configuration software**

Configuration is performed using the “BIS UHF Manager” software.

One requirement is that the processor is connected to the controlling system via the service interface (RS232). The configuration can be overwritten at any time.

The parameters can be saved in an XML file so that they can be retrieved whenever needed.



#### **Note**

Detailed information on the “BIS UHF Manager” can be found in the software's online help system.

---

- ▶ Start “BIS UHF Manager”.
- ▶ Click “Device Settings” and “Parameters...” in the menu bar.  
⇒ The “Parameters” window appears.

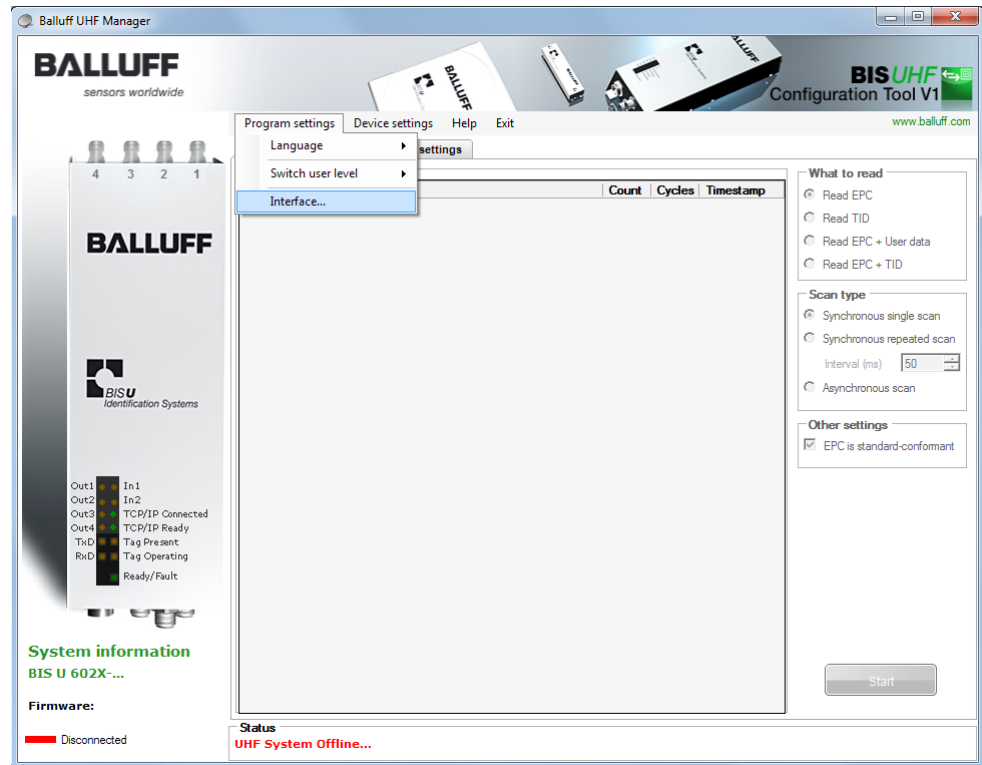


#### **Note**

Only the parameters listed in the following sections can be modified. The area for configuring advanced device parameters is password-protected and can only be accessed by a Balluff service technician.

---

## 7 Configuring the processor



- Start “BIS UHF Manager”.
  - ⇒ If “Connect on startup” was selected in the “Interface Settings” window (factory setting), the device automatically attempts to establish the last identified connection.

If the device is able to establish the last identified connection, “BIS connected...” appears in the status bar.

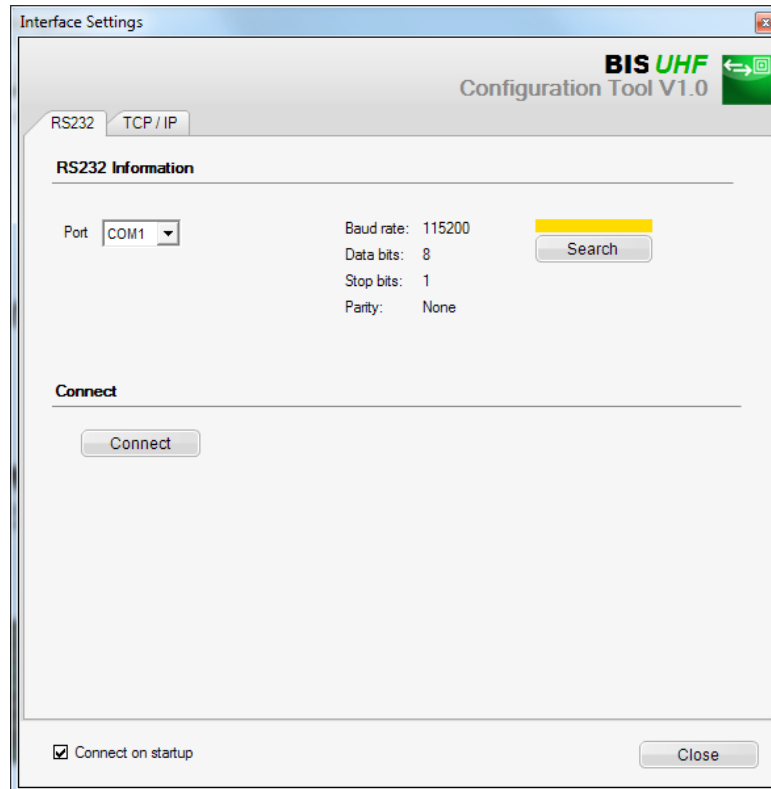
If the device is not able to establish a connection, “BIS not connected...” appears in the status bar.

The device must then be connected manually:

- Click “Program settings” and “Interface” in the menu bar.
  - ⇒ The “Interface Settings” window opens.

## 7 Configuring the processor

### Interface settings Service interface (RS232)



When the program starts, the device automatically connects if “Connect on startup” was selected in the “Interface Settings” window (factory setting).

When the “Interface Settings” window is opened, the last identified connection is displayed and the bar above the “Search” button is highlighted yellow.

- ▶ Click the “Search” button.
  - ⇒ The program searches for connections.

If the program finds a connection, the connection settings are displayed and the bar above the “Search” button is highlighted green.

- ▶ Click the “Connect” button.
  - ⇒ The device is connected.

If the program does not find a connection, the bar above the “Search” button is highlighted red.

## 7 Configuring the processor

### Device Settings

The screenshot shows the 'Parameters' window of the 'BIS UHF Configuration Tool V1.0'. The 'Device Settings' tab is active. It contains the following settings:

- Carrier follow-up time (s):** A numeric input field set to 5.
- Max. number of tags at one time:** A numeric input field set to 128.
- Environment factor rereadings:** A slider control.
- Reads:** A numeric input field set to 5.
- ETSI channels:** Four checkboxes labeled 4, 7, 10, and 13. The checkbox for 4 is checked.

At the bottom of the window, there are six buttons: 'Send To BIS', 'Retrieve From BIS', 'Save as...', 'Open...', 'Close', and 'Load Defaults'.

#### *Carrier follow-up time*

Follow-up time in seconds of the switched-on antennas after the command is sent. The read or write command should be executed within this time after it is detected.

Default setting: 5 seconds

#### *Max. number of tags at the same time*

Maximum number of data carriers expected in the field.

Default setting: 128

#### *Environment*

Factor rereadings (only for asynchronous detection or dynamic mode)

Number of rereadings after which a data carrier is reported as present (tag coming) or number of failed rereadings after which a data carrier is reported as not present (tag going) (only in dynamic mode).

Default setting: 5

#### *ETSI channels*

The channel setting determines the channel assignment. If multiple channels are activated, these are automatically selected by the device by means of the frequency hopping method.

Default setting: channel 4 switched on, channels 7...13 switched off

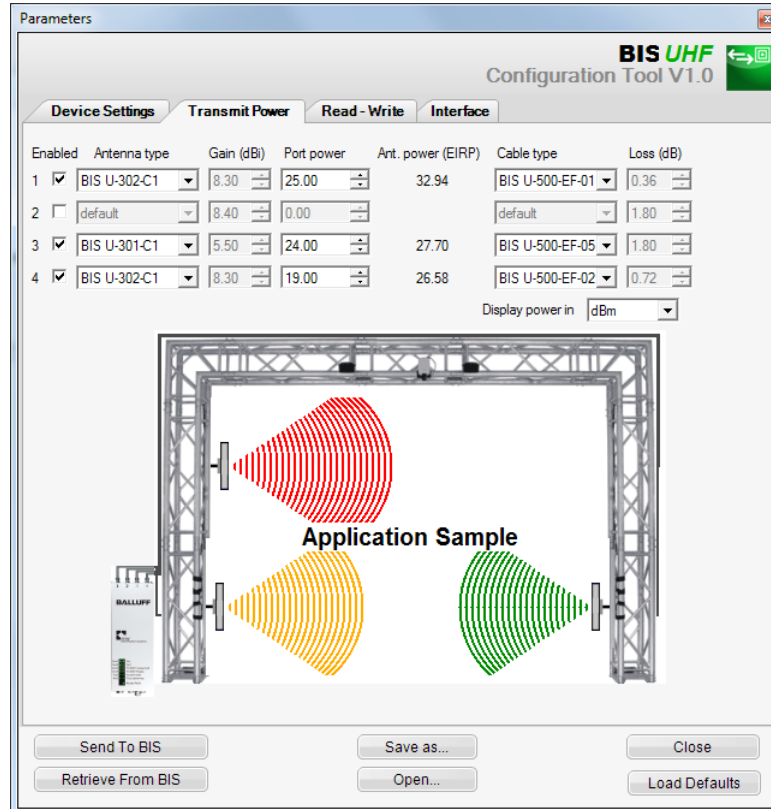


#### **Note**

The ETSI channels selection is only available when using the devices within the European Community.

## 7 Configuring the processor

### Transmit Power



#### Note

The *Gain* and *Loss* parameters are defined in the *Antenna type* and *Cable type* fields. These values are used to determine the maximum permissible radiated power.

The maximum permissible radiated power and factory settings differ depending on the set country profile. For information on the valid regulations of the different countries, see Chapter 2 “[Safety](#)”.

In the countries of the European Union, the radiated power is specified in the form of an ERP power (max. 2 watt<sub>ERP</sub>).

In the USA, Canada and Brazil, the radiated power is specified in the form of an EIRP power (max. 4 watt<sub>EIRP</sub>).

See the “Basic UHF manual” for more information on radiated powers.

## **7** Configuring the processor

### *Enabled:*

Enables/disables antennas 1...4.

Default setting: *antenna 1 enabled, antennas 2...4 disabled.*

### *Antenna type*

Selection of the used antenna.

Default setting: *BIS U-302-C1 or BIS U-302-C0*

### *Port power*

For selecting the power on the device (socket power).

Default setting: *22.5 dBm (176 mW) or 20.5 dBm (112 mW)*

### *Antenna power*

Power at the antenna (EIRP or ERP).

Default setting: *27 dBm (500 mW)*

### *Cable type*

Selection of the used cable.

Default setting: *BIS U-500-EF-05*



## 7 Configuring the processor

### Read - Write

The screenshot shows the 'Parameters' dialog box for the BIS UHF Configuration Tool V1.0. The 'Read - Write' tab is selected. Under the 'Tag Field Lengths' section, the 'User data start address' is set to 0, 'User data length (bytes)' is set to 16, 'TID length (bytes)' is set to 12, and 'EPC length (bits)' is set to Epc96. Under the 'Filtering' section, the option 'Keep identical records in scan results' is selected. At the bottom, there are buttons for 'Send To BIS', 'Retrieve From BIS', 'Save as...', 'Open...', 'Close', and 'Load Defaults'.

#### Tag Field Lengths area

##### *User data start address*

Start address of the USER data for automatic reading during data carrier searches and if USER data is used as an address during reading or writing.

Default setting: 0 bytes

##### *User data length*

Length of the USER data for automatic reading during data carrier searches and if USER data is used as an address during reading or writing. The value range is 1 to 16.

Default setting: 16 bytes

##### *TID length*

Length of the TID data with value range from 2 to 12.

Default setting: 12 bytes



#### Note

If data carriers have a length other than the TID set here, it is possible that they cannot be read from or written to.

## **7** Configuring the processor

### *EPC length*

Length of the EPC format on the data carriers. This parameter determines the maximum length of the EPC data to be processed and the output format for the command "Read multiple data carriers (EPC)".

Default setting: 96 bits



#### **Note**

If the actual EPC length of the data carriers is not equivalent to 96 bits, set the value to 496 bits. Otherwise the read and write commands cannot be run without errors.

---

## 8 Device function

### 8.1 Function principle of the BIS U-6028

Two buffers are needed to exchange data and commands between the processor and the host system. The buffer contents are exchanged using cyclical polling. The buffer content depends on the cycle in which it is written (e.g. control commands at the beginning of a job). When writing the buffer, the sent data from the preceding cycle are overwritten. Unwritten bytes are not deleted and retain their data content.

#### Total buffer

The buffer size of the total buffer corresponds to the plugged-in RT module. Allocation of this total buffer over the two antennas is performed using the "*Buffer 1*" parameter. To be able to read or write the USER data, a buffer size of at least 9 bytes is needed.

#### Example:

If a total buffer of 16 bytes is selected and the "*Buffer 1*" (*Antenna 1/3*) parameter is set to 10 bytes, 6 bytes then remain for antenna 2/4.

Two bytes less per antenna are available for data exchange, since the first and last byte of the respective data buffer is used for control and for status messages.

#### Output buffer

The control commands for the identification system and the data to be written to the data carrier are sent via the output buffer.

Subaddress \ Bit no.	7	6	5	4	3	2	1	0
00 <sub>hex</sub> = 1st bit header		TI	KA	HD		GR		AV
01 <sub>hex</sub>	Command designator or data							
02 <sub>hex</sub>	Start address (Low Byte) or data or number of bytes							
03 <sub>hex</sub>	Start address (Middle Byte) or data							
04 <sub>hex</sub>	Start address (High Byte) or data							
05 <sub>hex</sub>	Number of bytes (Low Byte) or data							
06 <sub>hex</sub>	Number of bytes (Middle Byte) or data							
07 <sub>hex</sub>	Number of bytes (High Byte) or data							
...	Data							
Last byte = 2nd bit header		TI	KA	HD		GR		AV

## 8 Device function

### Output buffer (continued)

#### Configuration and explanation (output buffer)

Subaddress	Bit name	Meaning	Function description
00 <sub>hex</sub> = bit header	TI	Toggle-bit in	Controller is ready to receive additional data (read job).
	KA	Antenna deactivation	Activates or deactivates the antenna selected with HD. 0: activated 1: deactivated
	HD	Antenna selection	Selection of the antennas for buffer 1 and buffer 2.  Buffer 1                      Buffer 2 0: antenna 1                0: antenna 2 1: antenna 3                1: antenna 4
	GR	Ground state	The processor goes into base state for the respective antenna. Any pending job is canceled.
	AV	Job	A job is pending for the respective antenna.

### Command designators

The device software (see part label) supports the following command IDs:

Command	Command designator	Until software version 1.1	Software version 1.2 and later
No command	00 <sub>hex</sub>	Yes	Yes*
Read data carrier (USER data)	01 <sub>hex</sub>	Yes	Yes
	81 <sub>hex</sub>	No	Yes*
Read EPC	03 <sub>hex</sub>	Yes	Yes
	42 <sub>hex</sub>	No	Yes*
Read TID	05 <sub>hex</sub>	Yes	Yes
	44 <sub>hex</sub> -	No	Yes*
Write data carrier (USER data)	02 <sub>hex</sub>	Yes	Yes
	82 <sub>hex</sub>	No	Yes*
Write EPC	04 <sub>hex</sub>	Yes	Yes
	43 <sub>hex</sub> -	No	Yes*
Write constant value (USER data)	32 <sub>hex</sub>	Yes	Yes
	B2 <sub>hex</sub>	No	Yes*
Set antenna power	45 <sub>hex</sub> -	No	Yes*
Read out antenna power	46 <sub>hex</sub> -	No	Yes*
Read multiple data carriers (EPC)	47 <sub>hex</sub> -	No	Yes*
Read number of tags	55 <sub>hex</sub> -	No	Yes*
Select (select data carrier)	40 <sub>hex</sub> -	No	Yes*
Unselect (unselect)	41 <sub>hex</sub> -	No	Yes*

\* This command ID is recommended for new systems since it is compatible with other BIS product families.

## 8 Device function

### Input buffer

The input buffer is used to send the data read by the identification system, the designations and the status codes to the controlling system.

Bit No. Subaddress	7	6	5	4	3	2	1	0
00 <sub>hex</sub> = 1st bit string	BB	HF	TO	AN	AF	AE	AA	TP
01 <sub>hex</sub>	Status code				or Data			
02 <sub>hex</sub>	Data							
...	Data							
Last byte = 2nd bit string	BB	HF	TO	AN	AF	AE	AA	TP

### Configuration and explanation (input buffer)

Subaddress	Bit name	Meaning	Function description
00 <sub>hex</sub> = bit string	BB	Ready	Processor unit is ready for operation.
	HF	Antenna error	Cable breakage at antenna or no antenna connected.
	TO	Toggle bit out	<b>Read operation:</b> additional data is made available by the processor unit. <b>Write operation:</b> processor unit can accept additional data.
	AN	Antenna	Selected antenna. Buffer 1                      Buffer 2 0: antenna 1                  0: antenna 2 1: antenna 3                  1: antenna 4
	AF	Job error	Error in processing the job or job canceled.
	AE	Job end	Confirmation – Job finished without error.
	AA	Job start	Confirmation – Job was recognized and started.
	TP	Tag present	Data carrier is in the range of the antenna (only in connection with read, write and list commands).

## 8 Device function

### Input buffer (continued)

#### Structure of the input buffer

The process data buffer is identical for all commands.

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Status code or data	<ul style="list-style-type: none"> <li>– If AF bit 1: provides information on the status of a query</li> <li>– If AF bit 0: data is written as with the individual commands</li> </ul>
...	Data	<ul style="list-style-type: none"> <li>– If AF bit 1: unused</li> <li>– If AF bit 0: data</li> </ul>
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

#### **i** Information

- The status code is only sent if the AF bit is set in the bit string.
- Because the read EPC can have varying lengths (number of bytes), a length field is sent. The maximum processed EPC length (12 bytes or 62 bytes) is configured.
- The TID is always sent in a 12-byte frame. The actual length within this frame is configured (see [Chapter "BUS Parameters", page 17](#) and [Chapter "Application Parameters", page 19](#)).

#### Status codes

#### **i** Information

Status codes are only valid in combination with the AF bit!

Subaddress	Function description
01 <sub>hex</sub>	Job cannot be executed because there is no active data carrier in the active range of the antenna.
02 <sub>hex</sub>	Not possible to read the data carrier.
03 <sub>hex</sub>	Data carrier was removed from the range of the antenna during reading.
04 <sub>hex</sub>	Cannot write to the data carrier.
05 <sub>hex</sub>	Data carrier was removed from the range of the antenna during writing.
07 <sub>hex</sub>	No or invalid command designator with set AV bit or the number of bytes is 00 <sub>hex</sub> .
09 <sub>hex</sub>	Cable breakage at antenna or no antenna connected.
0E <sub>hex</sub>	There is more than 1 data carrier or more than 1 selected data carrier in the active range of the antenna and the executed command is valid only for individual data carriers.
0F <sub>hex</sub>	First and second bit string not equal. The second bit string must be used.
43 <sub>hex</sub>	Error when reading or writing parameters of the internal memory.
44 <sub>hex</sub>	Arbitrary device behavior.
46 <sub>hex</sub>	Command outside the address range of the data carrier.
4E <sub>hex</sub>	No antenna activated.

## 8 Device function

### Communication

Communication between the controlling system and processor unit is defined by a sequence protocol. Communication between the controlling system and processor unit is implemented using control bit in the output and input buffer.

#### Basic sequence

1. The controller sends a command designator to the processor unit in the output buffer with the AV bit set. The AV bit tells the processor unit that a job is beginning and the transmitted data is valid.
2. The processor unit accepts the job and confirms the job by setting the AA bit in the input buffer.
3. If additional data needs to be exchanged for the job, readiness for additional data exchange is indicated by inverting the TI and TO toggle bits.
4. The processor unit has correctly executed the job and sets the AE bit in the input buffer.
5. The controller has accepted all data. The AV bit in the output buffer is reset.
6. The processor unit resets all control bits set in the input buffer during the job (AA bit, AE bit). The processor unit is ready for the next job.

#### Structure of the output buffer for various commands

##### Command designator 00<sub>hex</sub>: No command present

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	00 <sub>hex</sub> : No command present.
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

##### Command designator 81<sub>hex</sub> or 01<sub>hex</sub>: Read individual data carrier (USER data)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	81 <sub>hex</sub> : read data carrier (USER data).
02 <sub>hex</sub>	Start address 1 (Low Byte)	Start address (Low Byte) from which reading is to start.
03 <sub>hex</sub>	Start address 2 (Middle Byte)	Start address (Middle Byte) from which reading is to start.
04 <sub>hex</sub>	Start address 3 (High Byte)	Start address (High Byte) from which reading is to start.
05 <sub>hex</sub>	Number of bytes 1 (Low Byte)	The number of bytes (Low Byte) that are to be read starting from the start address.
06 <sub>hex</sub>	Number of bytes 2 (Middle Byte)	The number of bytes (Middle Byte) that are to be read starting from the start address.
07 <sub>hex</sub>	Number of bytes 3 (High Byte)	The number of bytes (High Byte) that are to be read starting from the start address.
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

## 8 Device function

### Command description (continued)

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Transmission of data that was read from the data carrier.
...	Data	Transmission of data that was read from the data carrier.  ... is continued, if necessary, in further buffer transmissions until the total number of bytes is reached.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

### Command designator 42<sub>hex</sub> or 03<sub>hex</sub>: Read individual data carrier (EPC)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	03 <sub>hex</sub> : Read data carrier (EPC).
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Number of bytes of the EPC read
...	Data	Transmission of EPC data that was read from the data carrier.  ... is continued, if necessary, in further buffer transmissions until the total number of bytes is reached.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.



## 8 Device function

### Command description (continued)

#### Command designator 44<sub>hex</sub> or 05<sub>hex</sub>: Read individual data carrier (TID)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	05 <sub>hex</sub> : read data carrier (TID).
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Transmission of TID data that was read from the data carrier.
...	Data	Transmission of TID data that was read from the data carrier. ... is continued, if necessary, in further buffer transmissions until the total number of bytes is reached.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

## 8 Device function

### Command description (continued)

#### Command designator 82<sub>hex</sub> or 02<sub>hex</sub>: Write to individual data carrier (USER data)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	82 <sub>hex</sub> : Write to data carrier (USER data).
02 <sub>hex</sub>	Start address 1 (Low Byte)	Start address (Low Byte) from which writing is to start.
03 <sub>hex</sub>	Start address 2 (Middle Byte)	Start address (Middle Byte) from which writing is to start.
04 <sub>hex</sub>	Start address 3 (High Byte)	Start address (High Byte) from which writing is to start.
05 <sub>hex</sub>	Number of bytes 1 (Low Byte)	The number of bytes that are to be written starting from the start address (Low Byte).
06 <sub>hex</sub>	Number of bytes 2 (Middle Byte)	The number of bytes that are to be written starting from the start address Middle Byte).
07 <sub>hex</sub>	Number of bytes 3 (High Byte)	The number of bytes that are to be written starting from the start address (High Byte).
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

Data is accepted from the processor unit only after the command has been accepted by the processor unit and acknowledged.

00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Transmission of the data that is to be written to the data carrier.
...	Data	Transmission of the data that is to be written to the data carrier.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

## 8 Device function

### Command description (continued)

#### Command designator 43<sub>hex</sub> or 04<sub>hex</sub>: Write to individual data carrier (EPC)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	04 <sub>hex</sub> : Write to data carrier (EPC).
02 <sub>hex</sub>	No. of bytes	Number of bytes (1...62) to be written beginning with the start address 00 <sub>hex</sub> .
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

Data is accepted from the processor unit only after the command has been accepted by the processor unit and acknowledged.

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Transmission of the data that is to be written to the data carrier.
...	Data	Transmission of the data that is to be written to the data carrier.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

#### Command designator B2<sub>hex</sub> or 32<sub>hex</sub>: Write constant value to individual data carrier (USER data)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	B2 <sub>hex</sub> : Write to data carrier (USER data).
02 <sub>hex</sub>	Start address 1 (Low Byte)	Start address (Low Byte) from which writing is to start.
03 <sub>hex</sub>	Start address 2 (Middle Byte)	Start address (Middle Byte) from which writing is to start.
04 <sub>hex</sub>	Start address 3 (High Byte)	Start address (High Byte) from which writing is to start.
05 <sub>hex</sub>	Number of bytes 1 (Low Byte)	The number of bytes that are to be written starting from the start address (Low Byte).
06 <sub>hex</sub>	Number of bytes 2 (Middle Byte)	The number of bytes that are to be written starting from the start address Middle Byte).
07 <sub>hex</sub>	Number of bytes 3 (High Byte)	The number of bytes that are to be written starting from the start address (High Byte).
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

Data is accepted from the processor unit only after the command has been accepted by the processor unit and acknowledged.

00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	Value that is to be written to the data carrier.
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

## 8 Device function

### Command description (continued)

#### Command designator 45<sub>hex</sub>: Set antenna power

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	45 <sub>hex</sub> : Set antenna power
02 <sub>hex</sub>	Antenna power	<p>Antenna power for the current antenna (head) in increments of 0.25 dBm</p> <p>Permitted value range (decimal):  <b>BIS U-6028-048-104-...</b> :  68 (+17.00 dBm ERP)...132 (+33.00 dBm ERP)</p> <p><b>BIS U-6028-048-114-...</b> and <b>BIS U-6028-048-134-...</b> :  77 (+19.25 dBm EIRP)...144 (+36.00 dBm EIRP)</p> <p>The set power is not permanently saved and is reset to the saved default value when the reader is booted.</p> <p>The socket power on the device is calculated and set based on the configured antenna/cable parameters.</p>
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

#### Command designator 46<sub>hex</sub>: Read out antenna power

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	46 <sub>hex</sub> : Read out antenna power
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Antenna power	Antenna power for the current antenna (head) in increments of 0.25 dBm or 0 for antenna that is switched off
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

## 8 Device function

### Command description (continued)

#### Command designator 47<sub>hex</sub>: Read multiple data carriers (EPC)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	47 <sub>hex</sub> : Read multiple data carriers (EPC)
02 <sub>hex</sub>	Type	0 = EPC (other values currently not supported)
03 <sub>hex</sub>	Max Number of Data Carriers	Maximum number of data carriers to be output 1...255, (0 = no limitation) If the number is greater than the values listed under "Multi-tagging" on page 13, then the lower value applies.
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Number of data carriers read	1...255
02 <sub>hex</sub>	Number of bytes per EPC	12 or 64 This corresponds to the length of the longest transmitted EPC configured in the device. EPCs shorter than this length are output right-justified and filled with zeros on the left. In the following, the (number of data carriers read) × (number of bytes per EPC) are transmitted. For 64 bytes per EPC, the actual EPC length in ASCII is specified in the 1st and 2nd byte of the EPC.
03 <sub>hex</sub>	Data of 1st EPC	Actual EPC data
...	Data of 1st EPC	Actual EPC data
...	Data of 1st EPC	Actual EPC data
...	Data of 2nd EPC	Actual EPC data
...	Data of 2nd EPC	Actual EPC data
...	Data	... is continued, if necessary, in further buffer transmissions until the total number of bytes is reached.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

This command always responds immediately—even for configured dynamic mode—with the currently identified number of tags.

If no tag is identified, this command generates an error message (status code 01).

## 8 Device function

### Command description (continued)

#### Command designator 55<sub>hex</sub>: Read number of tags

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	55 <sub>hex</sub> : Read number of tags
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

If execution is successful, the response is passed to the input buffer in the following format:

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Number of data carriers read	0...255
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

This command always responds immediately—even for configured dynamic mode—with the currently identified number of tags.

If no tag is identified, this command returns the number "0" and no error message.

## 8 Device function

### Command description (continued)

#### Command designator 40<sub>hex</sub>: Select (data carrier selection for multi-tagging)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	40 <sub>hex</sub> : Select tag (selection of the data carrier to be used for further processing steps such as reading or writing)
02 <sub>hex</sub>	Type	0 = EPC (other values currently not supported)
03 <sub>hex</sub>	No. of bytes	Number of bytes of the data carrier identifier (EPC) that is transmitted in following cycles.
04 <sub>hex</sub>	Reserved	Reserved for expansions; please set to 0.
05 <sub>hex</sub>	Reserved	Reserved for expansions; please set to 0.
06 <sub>hex</sub>	Reserved	Reserved for expansions; please set to 0.
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

Data of the data carrier identifier is accepted from the processor unit only after the command has been accepted by the processor unit and acknowledged.

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Data	1st byte of the data carrier identifier (EPC or TID)
...	Data	Other bytes of the data carrier identifier (EPC or TID) ... is continued, if necessary, in further buffer transmissions until the total number of bytes is reached.
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

After the Select command, read/write commands (command designators 01<sub>hex</sub>, 02<sub>hex</sub>, 03<sub>hex</sub>, 04<sub>hex</sub>, 05<sub>hex</sub>, 32<sub>hex</sub>, 42<sub>hex</sub>, 43<sub>hex</sub>, 44<sub>hex</sub>, 81<sub>hex</sub>, 82<sub>hex</sub>, B2<sub>hex</sub>) for the corresponding antenna are run only on the designated data carrier, if it is available.

If the selected data carrier is not in the field of the antenna at the moment, the Select command is processed without errors anyway, but following read/write commands return an error with status code 01<sub>hex</sub> (no data carrier).

If the selected data carrier identifier is present on more than one tag, the following commands are run as follows:

- Read commands are run on **one** data carrier, which is randomly selected from the suitable data carriers.
- Write commands are run on **all** suitable data carriers.

## 8 Device function

### Command description (continued)



#### Information

- The data carrier identifier is usually taken from a preceding command 47<sub>hex</sub>: *Read multiple data carriers (EPC)*. Omit the leading fill bytes in the data carrier list for this. The entire entry is usually used for the 12-byte EPC format; for the 64-byte format (as ASCII digits in byte address 0 and 1 of the respective entry), read the actual length and then read out the identifier starting from the byte address (64-length).

Example: Length specification = "24" means that the EPC is in byte address 40...63.

- If multiple data carriers are to be processed in sequence, what usually results is the following command sequence:

Command 47<sub>hex</sub>: Read multiple data carriers (EPC)

Command 40<sub>hex</sub>: Select (1st identifier)  
... Process 1st data carrier

Command 40<sub>hex</sub>: Select (2nd identifier)  
... Process 2nd data carrier

Command 40<sub>hex</sub>: Select (3rd identifier)  
... Process 3rd data carrier

etc.

Command 41<sub>hex</sub>: Unselect

The controller can choose the sequence of data carriers at random, omit data carriers or select the same one repeatedly.

- With the BIS U-602\_ devices the selection is made only using the EPC, thereby also enabling operation of multiple antennas at one read position. Then a data carrier with a suitable data carrier identifier is also read if it is located in front of an antenna **other** than the one to which the Select command refers. If you need to ensure that only data carriers in front of the current antenna are read after a Select command, the EPC identifiers of the data carrier must be unique **and** the presence of the data carrier in front of the desired antenna must first be checked using command 47<sub>hex</sub>: *Read multiple data carriers (EPC)*.
- A data carrier selection for an antenna remains valid until one of the following events occurs:
  - A new selection is defined.
  - An Unselect command undoes the selection.
  - The GR bit (basic state) for the corresponding antenna is set.
  - The device is restarted.



## 8 Device function

### Command description (continued)

#### Command designator 41<sub>hex</sub>: Unselect (undo the data carrier selection)

Subaddress	Meaning	Function description
00 <sub>hex</sub>	1st bit string	
01 <sub>hex</sub>	Command designator	41 <sub>hex</sub> : Unselect (undo the fixed data carrier selection)
...	None	No meaning
Last byte	2nd bit string	If first and second bit strings agree, there is valid data present.

The Unselect command undoes a data carrier selection for an antenna. If no selection was made, the status remains unchanged.

Subsequent read/write commands then refer to any individual data carrier in the field of the antenna. If multiple data carriers are in the field of the antenna, the following read/write commands are ended with an error and status code 0E<sub>hex</sub> (multiple data carriers).

## 8 Device function

### 8.2 Function indicators

The operating states of the identification system and the PROFINET connection are indicated via LEDs.

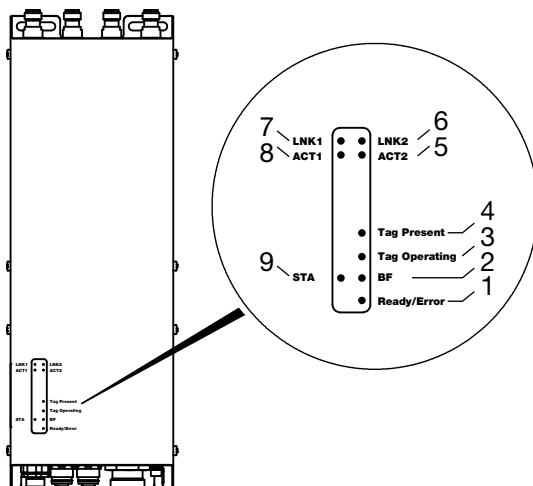


Fig. 7: Function indicators

#### Identification system

- |                    |                          |                          |
|--------------------|--------------------------|--------------------------|
| 1 Ready/Error      | 4 Tag Present            | 7 Port 1 Link (LNK1)     |
| 2 Bus Failure (BF) | 5 Port 2 Activity (ACT2) | 8 Port 1 Activity (ACT1) |
| 3 Tag Operating    | 6 Port 2 Link (LNK2)     | 9 Status (STA)           |

#### Start-up phase

The “Ready/Error” LED flashes green during the start-up phase. When setup is finished and the system is ready for operation, the “Ready/Error” LED lights up green.

## 8 Device function

### Diagnostics

#### Identification system

Status LED	Meaning
Ready / Error	
Off	Device is not ready for operation
Green, lit	Device is ready for operation
Green, flashing	Startup phase of the device (Setup)
Red, flashing	Error (e.g. device error or broken cable)

Tag operating	
Off	No command
Yellow, lit	Command to data carrier (e.g. detect, read or write)

Tag present	
Off	No command
Yellow, flashing	No data carrier detected in the active range of the antenna
Yellow, lit	Data carrier detected in the active range of the antenna

#### Ethernet and PROFINET connection

STA (Status)	
Off	PROFINET: not yet ready
Yellow, lit	PROFINET: ready

BF (Bus Failure)	
Off	PROFINET: connection established
Yellow, lit	PROFINET: no connection or configuration

LNK1 / LNK2 (Link)	
Off	Ethernet: no connection
Yellow, lit	Ethernet: connection OK
Yellow, flashing	DCP flashing activated

ACT1 / ACT2 (Activity)	
Off	Ethernet: no activity
Yellow, lit	Ethernet: RX- / TX-activity

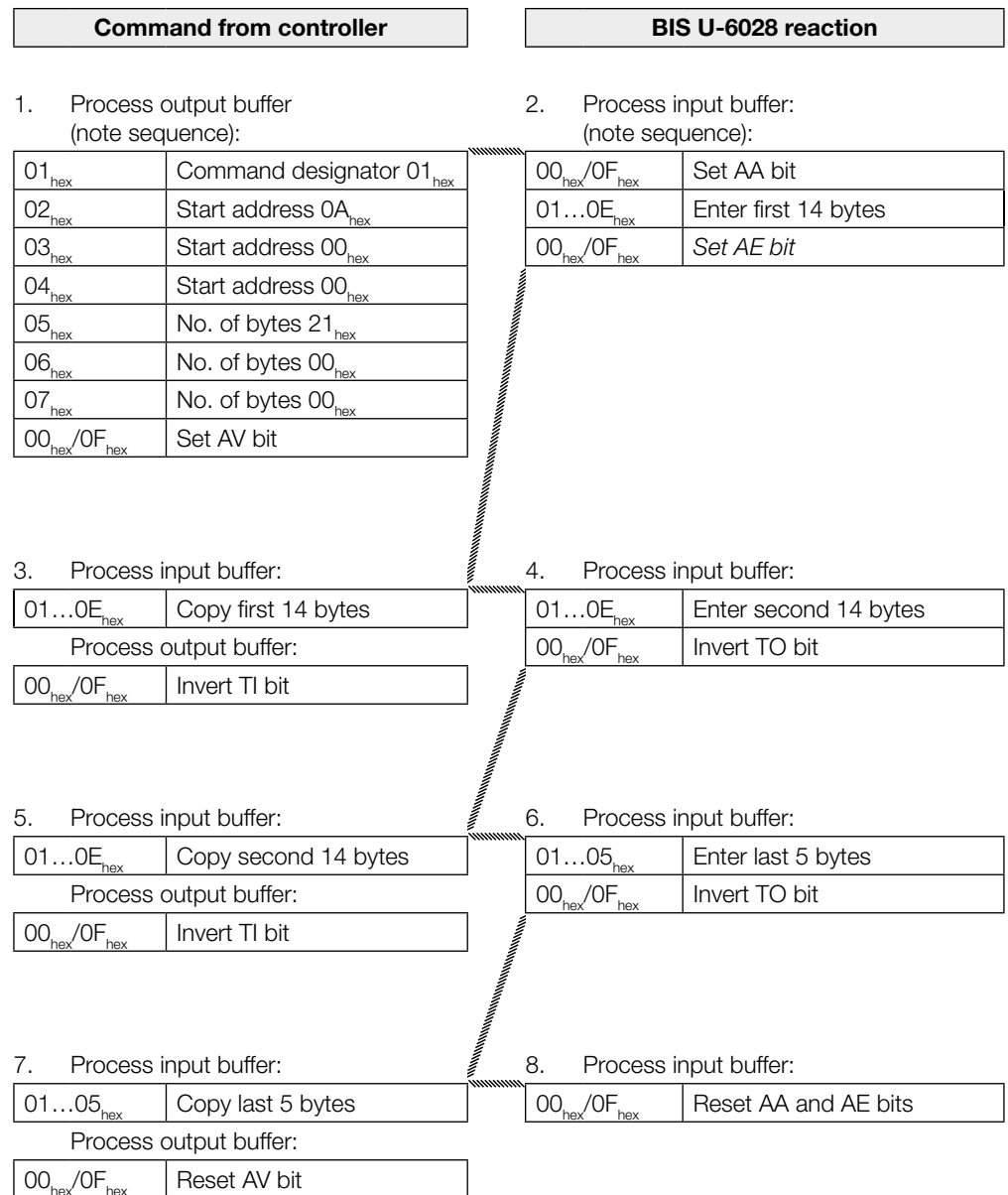
## 8 Device function

### 8.3 Examples

#### 1st example

**Read 33 bytes of USER data starting at data carrier address 10**

**For configuration  
with 16-byte  
buffer size!**

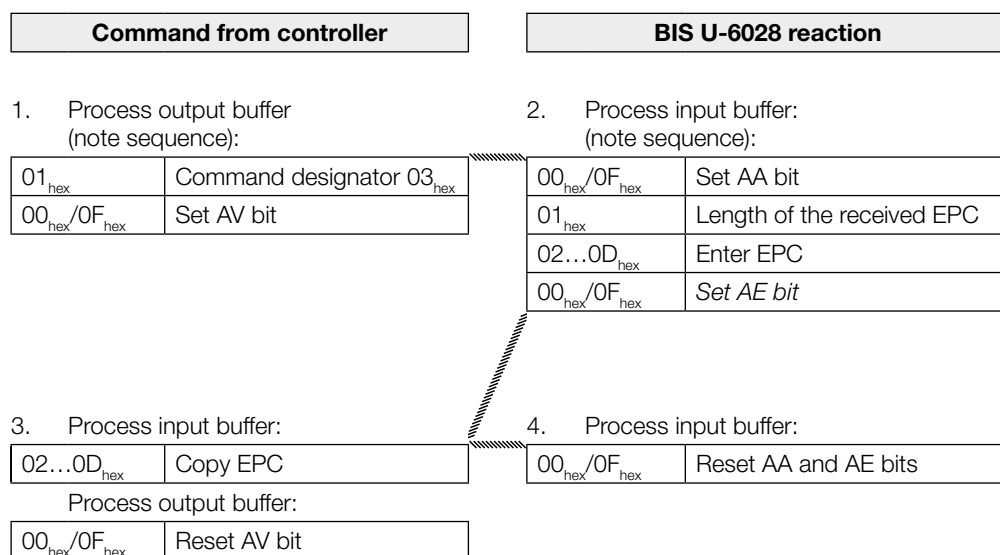


## 8 Device function

### 2nd example

### Read the EPC of the data carrier

**For configuration  
with buffer size of  
16 bytes and  
EPC length of  
12 bytes!**



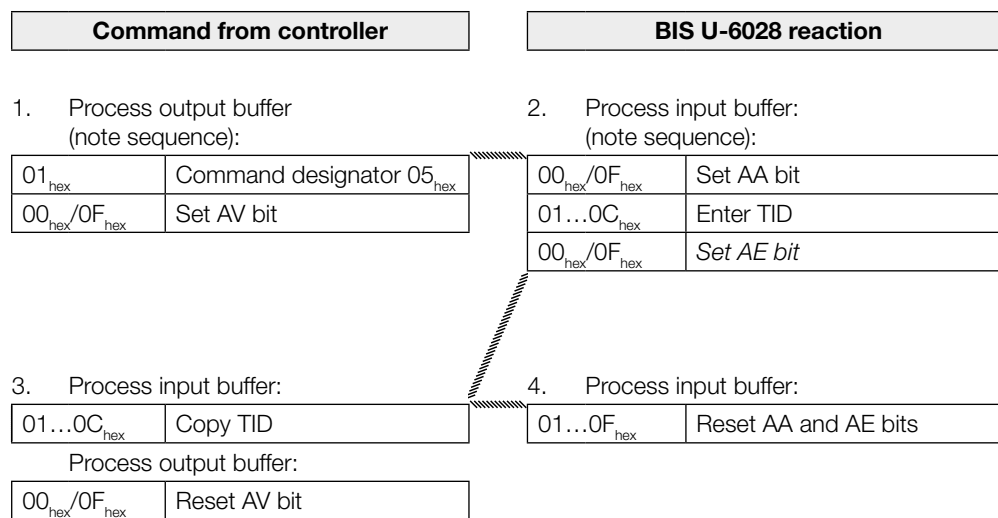
## 8 Device function

### 3rd example

### Read the TID of the data carrier

**For configuration  
with 16-byte  
buffer size!**

If the TID length configured in the UHF manager is shorter than 12 bytes, leading zeros are used to pad the TID to 12 bytes.



## 8 Device function

### 4th example

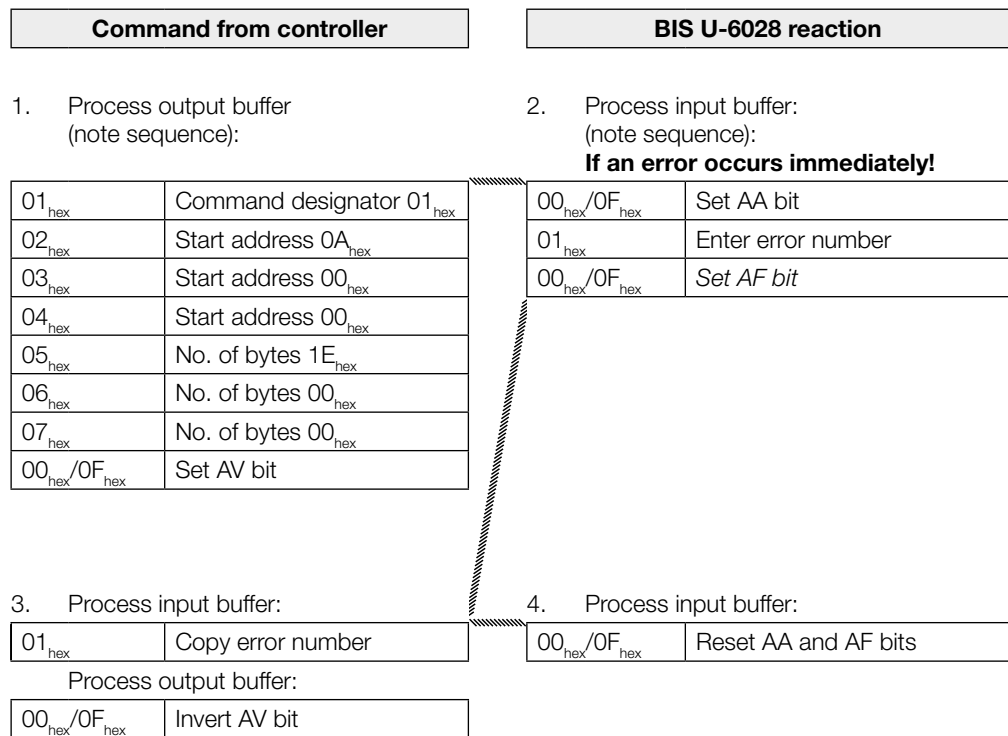
### Read 30 bytes of USER data starting at data carrier address 10 with read error

**For configuration  
with 16-byte  
buffer size!**



#### Information

If an error occurs, the AF bit is set instead of the AE bit, together with a corresponding error number. Setting the AF bit cancels the job and declares it as finished.

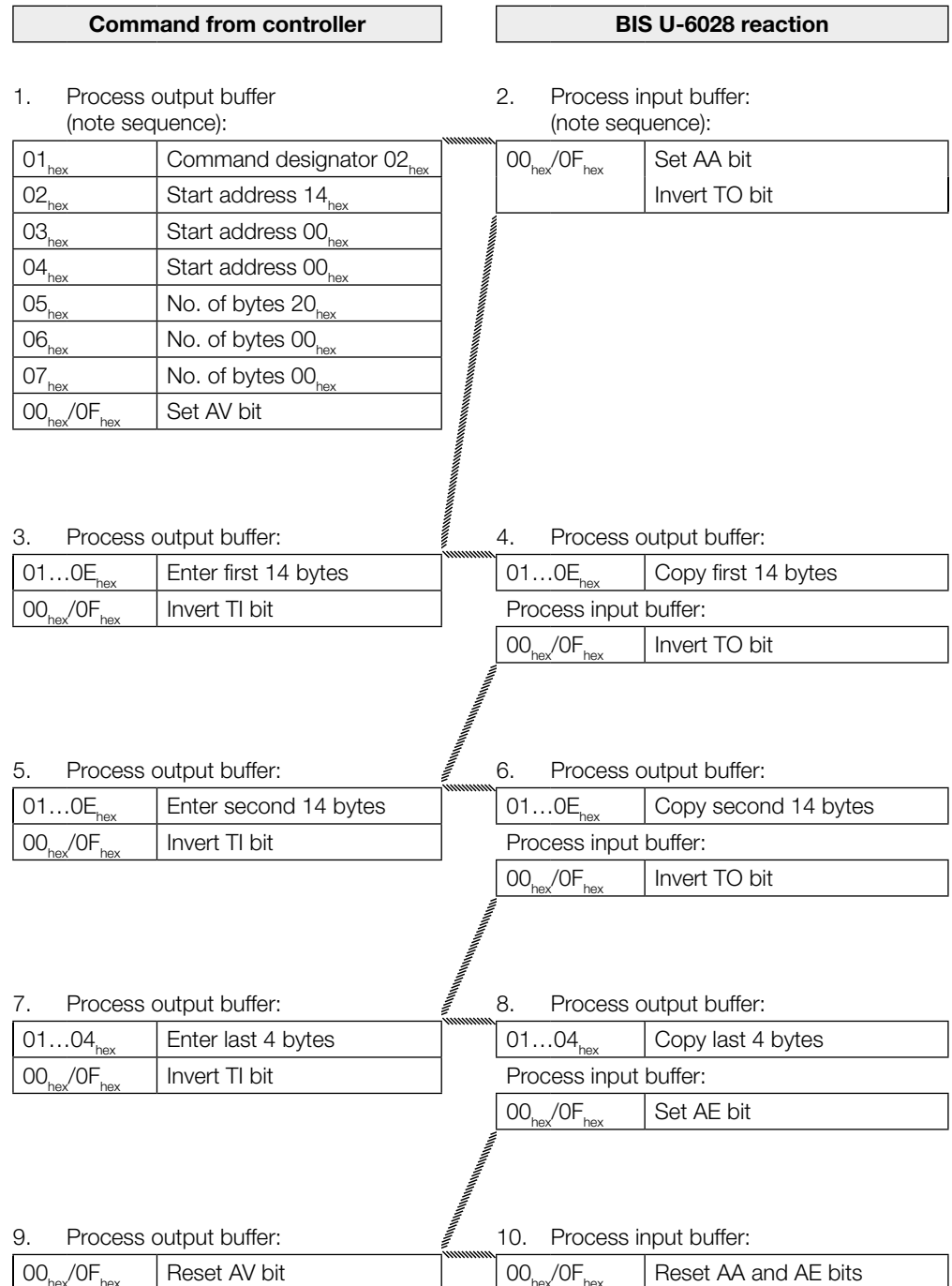


## 8 Device function

### 5th example

**Write 32 bytes of USER data starting at data carrier address 20**

**For configuration  
with 16-byte  
buffer size!**



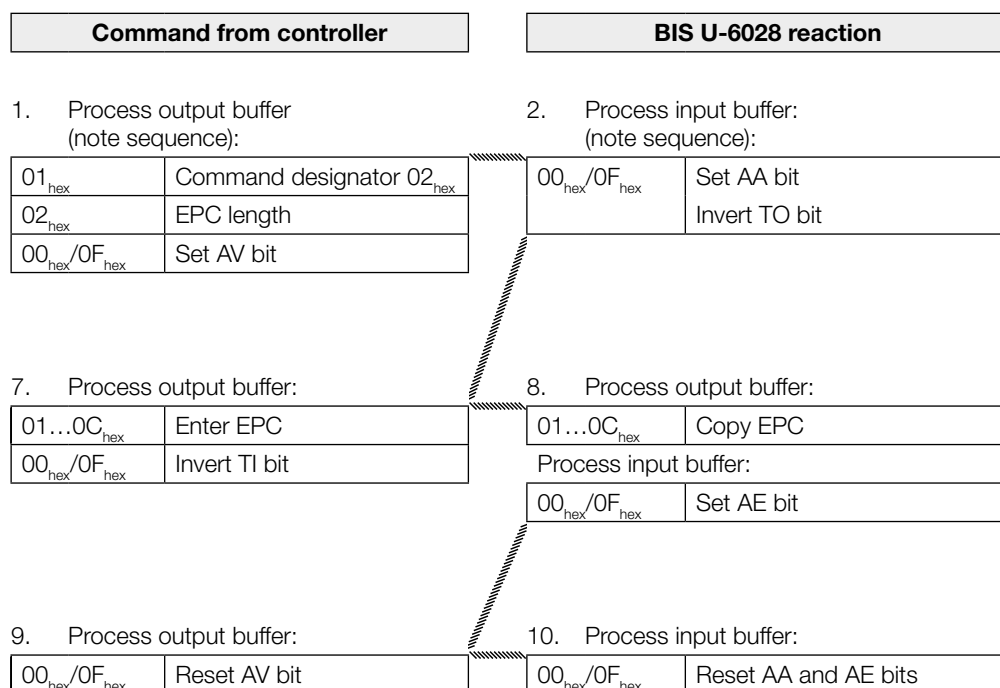


## 8 Device function

### 6th example

### Write 12 bytes of EPC on the data carrier

For configuration  
with 16-byte  
buffer size!

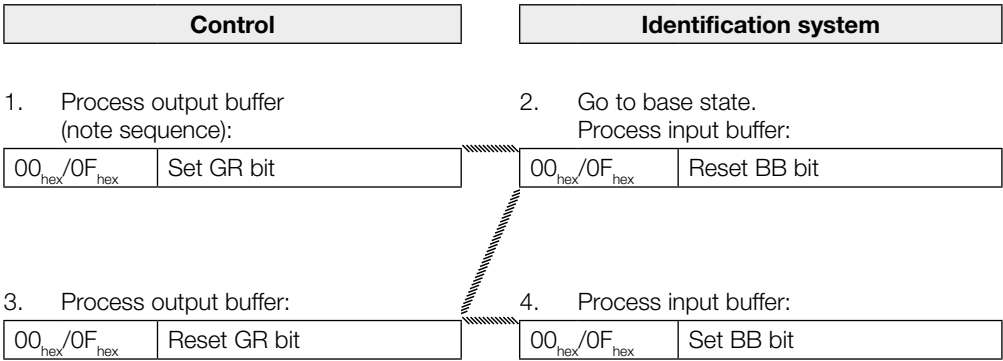


**8** Device function

**7th example      Establish base state of antenna 1**

**For configuration  
with 16-byte  
buffer size!**

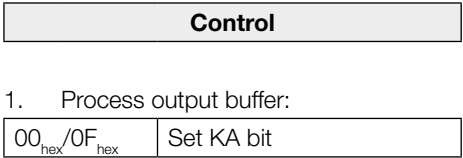
The antennas of the BIS U identification system can be set to the base state independent of one another.



**8th example      Switch off antennas**

**For configuration  
with 16-byte  
buffer size!**

In normal operation, both antennas are switched on. By setting the KA bit, the antenna selected by the HD bit can be switched off (antenna 1 or 3 for buffer 1, antenna 2 or 4 for buffer 2).



The antennas are switched back on by resetting the KA bit.

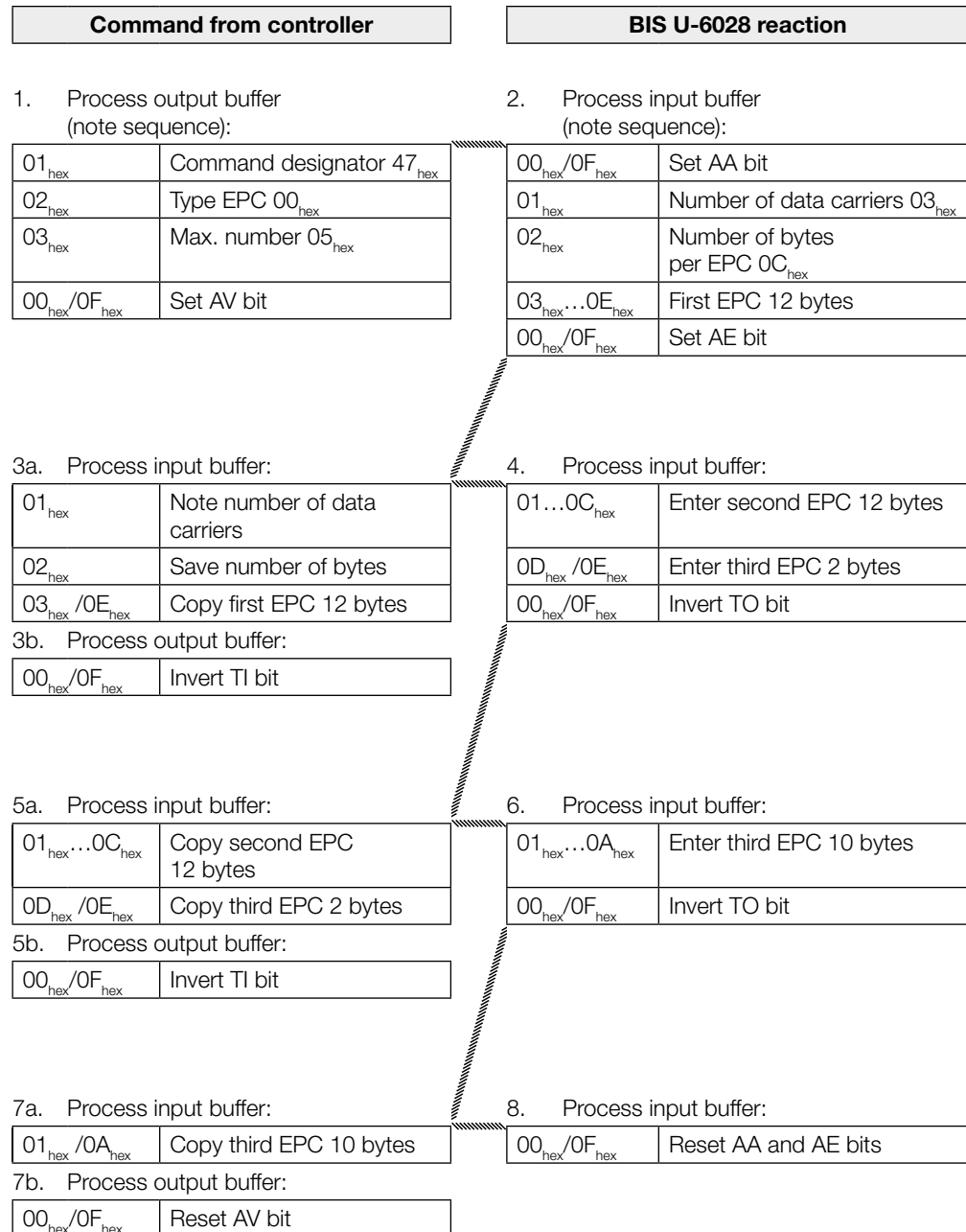
## 8 Device function

### 9th example

### Read the EPCs of multiple data carriers in front of the antenna

**For configuration  
with 16-byte  
buffer size!**

With a maximum number of 5, EPC size of 12 bytes configured, 3 data carriers identified



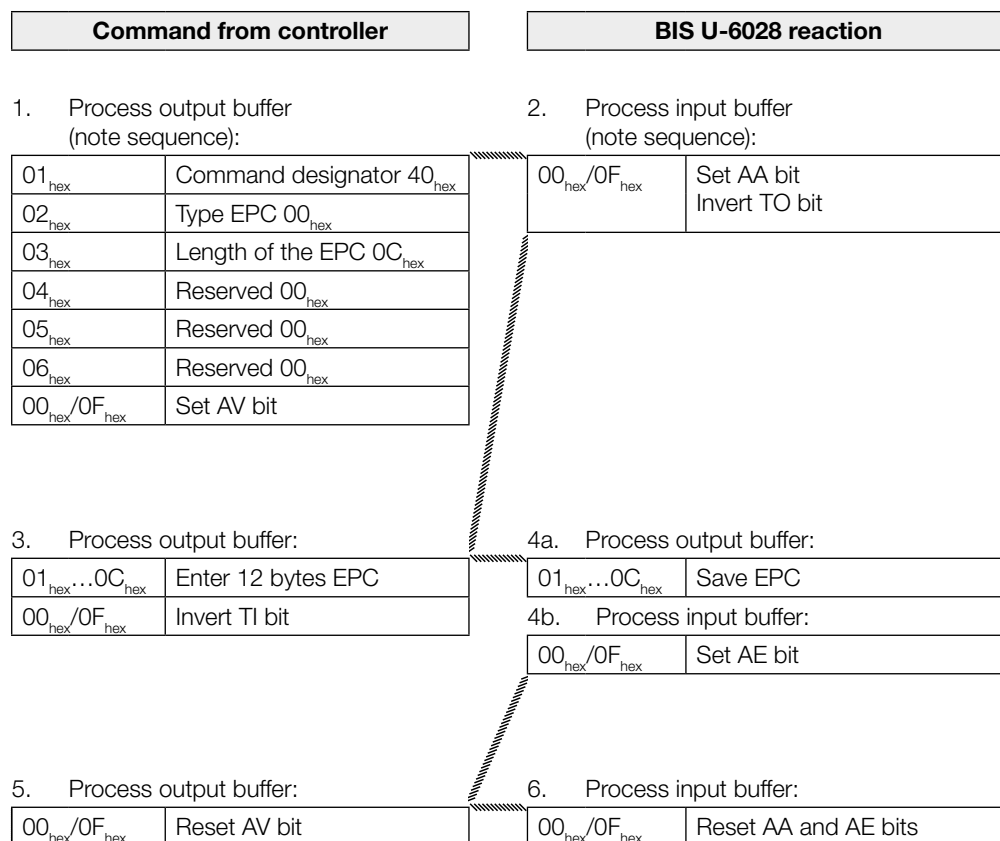
## 8 Device function

### 10th example

### Select a data carrier for further processing

**For configuration with 16-byte buffer size!**

For configuration with EPC size of 12 bytes



Appendix

Type code

	BIS	U	-	6028	-	048	-	104	-	06	-	ST28
Balluff identification system												
Series U read/write system												
Hardware type												
6020 = Serial interface RS232 (metal housing)												
6026 = EtherNet/IP (metal housing)												
6027 = Ethernet TCP/IP (metal housing)												
6028 = PROFINET (metal housing)												
Software type												
034 = Balluff protocol EtherNet/IP												
048 = Balluff protocol PROFINET												
053 = Balluff protocol RS232 UHF for Europe												
054 = Balluff protocol Ethernet TCP/IP UHF for Europe												
059 = Balluff protocol RS232 UHF for USA/Canada/Mexico/Brazil/China/Japan etc.												
060 = Balluff protocol Ethernet TCP/IP UHF for USA/Canada/Mexico/Brazil/China/Japan etc.												
Antenna socket version												
10_ = Country setting 865...868 MHz Europe												
11_ = Country setting 902...928 MHz USA/Canada/Mexico/Argentina												
12_ = Country setting 920.5...924.5 MHz China												
13_ = Country setting 915...928 MHz Brazil												
15_ = Country setting 916.8...920.4 MHz Japan												
17_ = Country setting 920...926 MHz Australia												
_4 = 4 antenna sockets												
Interface												
00 = RS232												
06 = Ethernet												
Customer connection												
ST22 = for PROFINET device with AIDA recommendation												
ST26 = for serial device												
ST27 = for TCP/IP device												
ST28 = for PROFINET device												
ST35 = for EtherNet/IP device												

**Accessories**  
**(optional, not**  
**included in scope**  
**of delivery)**

**Type**

Mounting plates

**Order designation**

BIS Z-HW-004



**Note**

You can find more accessories for the BIS U-6028-... in the Balluff BIS catalog and under [www.balluff.com](http://www.balluff.com).

Appendix

ASCII table

Decimal	Hex	Control code	ASCII	Decimal	Hex	ASCII	Decimal	Hex	ASCII
0	00	Ctrl @	NUL	43	2B	+	86	56	V
1	01	Ctrl A	SOH	44	2C	,	87	57	W
2	02	Ctrl B	STX	45	2D	-	88	58	X
3	03	Ctrl C	ETX	46	2E	.	89	59	Y
4	04	Ctrl D	EOT	47	2F	/	90	5A	Z
5	05	Ctrl E	ENQ	48	30	0	91	5B	[
6	06	Ctrl F	ACK	49	31	1	92	5C	\
7	07	Ctrl G	BEL	50	32	2	93	5D	]
8	08	Ctrl H	BS	51	33	3	94	5E	^
9	09	Ctrl I	HT	52	34	4	95	5F	_
10	0A	Ctrl J	LF	53	35	5	96	60	`
11	0B	Ctrl K	VT	54	36	6	97	61	A
12	0C	Ctrl L	FF	55	37	7	98	62	B
13	0D	Ctrl M	CR	56	38	8	99	63	c
14	0E	Ctrl N	SO	57	39	9	100	64	d
15	0F	Ctrl O	SI	58	3A	:	101	65	e
16	10	Ctrl P	DLE	59	3B	;	102	66	f
17	11	Ctrl Q	DC1	60	3C	<	103	67	g
18	12	Ctrl R	DC2	61	3D	=	104	68	h
19	13	Ctrl S	DC3	62	3E	>	105	69	i
20	14	Ctrl T	DC4	63	3F	?	106	6A	j
21	15	Ctrl U	NAK	64	40	@	107	6B	k
22	16	Ctrl V	SYN	65	41	A	108	6C	L
23	17	Ctrl W	ETB	66	42	B	109	6D	m
24	18	Ctrl X	CAN	67	43	C	110	6E	n
25	19	Ctrl Y	EM	68	44	D	111	6F	o
26	1A	Ctrl Z	SUB	69	45	E	112	70	p
27	1B	Ctrl [	ESC	70	46	F	113	71	q
28	1C	Ctrl \	FS	71	47	G	114	72	r
29	1D	Ctrl ]	GS	72	48	H	115	73	s
30	1E	Ctrl ^	RS	73	49	I	116	74	t
31	1F	Ctrl _	US	74	4A	J	117	75	u
32	20		SP	75	4B	K	118	76	V
33	21		!	76	4C	L	119	77	W
34	22		"	77	4D	M	120	78	X
35	23		#	78	4E	N	121	79	Y
36	24		\$	79	4F	O	122	7A	Z
37	25		%	80	50	P	123	7B	{
38	26		&	81	51	Q	124	7C	
39	27		'	82	52	R	125	7D	}
40	28		(	83	53	S	126	7E	~
41	29		)	84	54	T	127	7F	DEL
42	2A		*	85	55	U			

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