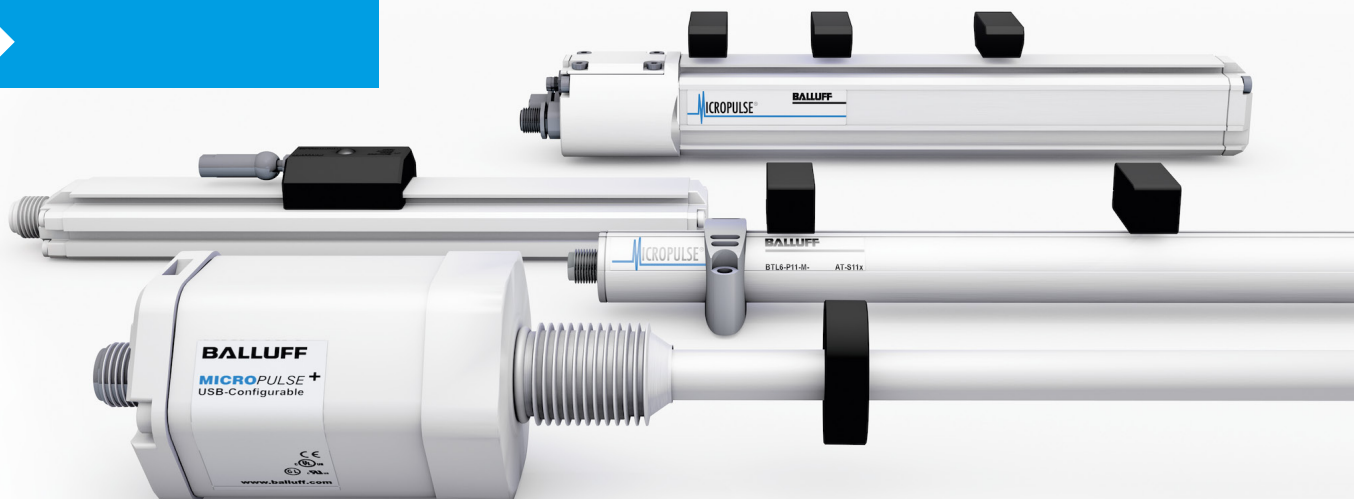
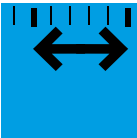


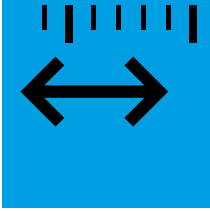
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Transducer with Real-Time Ethernet

Highly dynamic, synchronous and accurate





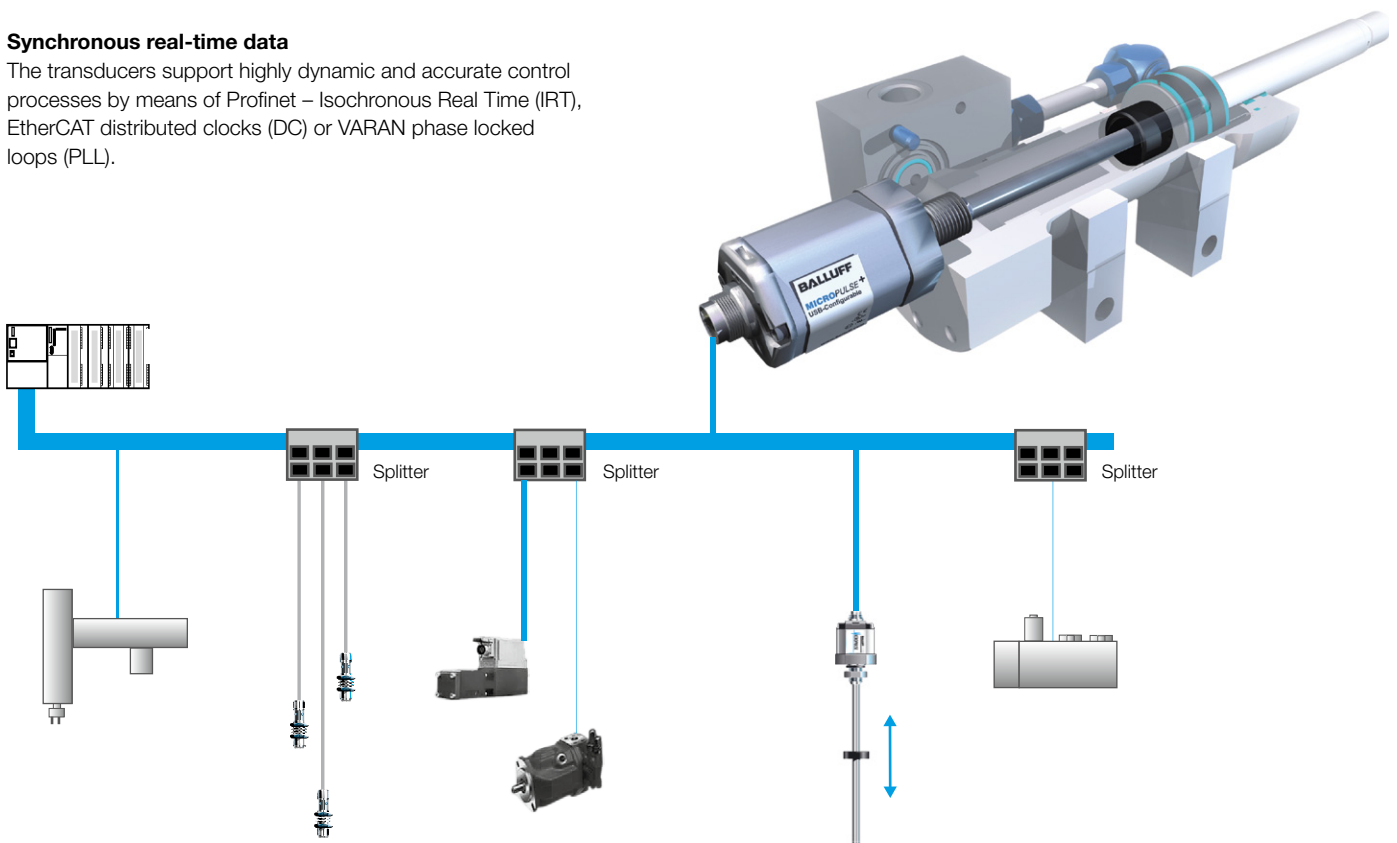
Transducer with real-time Ethernet interfaces

Benefits

- Fast, accurate and absolute position and speed measurement
- Non-contact and wear-free, insensitive to contamination
- Shock and vibration-resistant
- Easy and time-saving integration into the controller through defined parameter data exchange
- 4 designs – 3 interfaces

Synchronous real-time data

The transducers support highly dynamic and accurate control processes by means of Profinet – Isochronous Real Time (IRT), EtherCAT distributed clocks (DC) or VARAN phase locked loops (PLL).



32 measured values with a single measurement

Micropulse transducers of the BTL7-V series are capable of detecting and processing up to 16 position encoders. Two values can be output for each position encoder: the position and the speed.

Flexible magnet mode

The BTL7-V series can be operated as a 1...16 magnet type. The sensor automatically detects how many magnets are in the measuring range. This function makes it easier to operate applications with a changing number of magnets.

Product Overview

Rod and profile housings of the Micropulse transducer BTL



| Series | | BTL6-V1 | BTL7-V50 | BTL6-V1 | BTL6-V55 | BTL7-V50 |
|---------------------------------------|--------------|------------------------------|------------------------------|----------------|---------------|--------------|
| Interface | Profinet IRT | No | Yes | No | No | Yes |
| | EtherCAT | Yes *1) | Yes | Yes *1) | No | Yes |
| | VARAN | Yes | No | Yes | Yes | No |
| Design | | Rod | Rod | Profile, round | Profile, flat | Profile |
| Max. measuring length | | 4012 mm | 7620 mm | 4012 mm | 4572 mm | 7620 mm |
| Resolution | | < 10 µm | < 1 µm | < 10 µm | < 10 µm | < 1 µm |
| Repeat accuracy | | < 30 µm | ≤ ±5 µm | < 30 µm | < 20 µm | ≤ ±5 µm |
| Max. scan rate | | 2 kHz | 1.1 kHz | 2 kHz | 4 kHz | 1.1 kHz |
| Max. measurable speed | | 10 m/s | 10 m/s | 10 m/s | 10 m/s | 10 m/s |
| Max. number of position encoders | | 2 | 16 | 2 | 2 | 16 |
| Supply voltage | | 20...28 V DC | 10...30 V DC | 20...28 V DC | 10...30 V DC | 10...30 V DC |
| Operating temperature | | 0...+70 °C | -40...+85 °C | 0...+70 °C | 0...+85 °C | -40...+85 °C |
| Housing material | | Aluminum, Stainless steel | Aluminum, Stainless steel | Aluminum | Aluminum | Aluminum |
| Degree of protection as per IEC 60529 | | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 |

*1) No distributed clocks function

Ordering example

BTL7-V50 - M - - C003

Interface

T = Profinet IRT
E = EtherCAT

Rated length (4-digit)

Design

P = Profile housing
B = Metric mounting thread M18x1.5/O-ring, rod diameter 10.2 mm
Z = 3/4" thread 16 UNF/O-ring, rod diameter 10.2 mm

BTL6-V - M - - S115

Interface

11E = EtherCAT, 1 position encoder
12E = EtherCAT, 2 position encoders
11V = VARAN, 1 position encoder
12V = VARAN, 2 position encoders
55V = VARAN, Euromap 75

Rated length (4-digit)

Design

A1 = Profile housing, round
PF = Profile housing, flat
B = Metric mounting thread M18x1.5/O-ring/rod diameter 10.2 mm
Z = 3/4" thread 16 UNF/O-ring, rod diameter 10.2 mm



| Series | BTL-P-1013-4R | BTL-P-1012-4R | BTL-P-1013-4S | BTL5-P-3800-2 | BTL6-A-3801-2 | BTL5-F-2814-1S |
|----------|--------------------------|---------------|---------------|------------------------------|---------------|----------------|
| | Position encoder for rod | | | Position encoder for profile | | |
| Distance | Captive | Captive | Captive | 0.1...4 mm | 4...8 mm | Captive |

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Systems and Service



Industrial Networking and Connectivity



Industrial Identification



Object Detection



Linear Position Sensing and Measurement



Condition Monitoring and Fluid Sensors



Accessories

Headquarters

Balluff GmbH
Schurwaldstrasse 9
73765 Neuhausen a.d.F.
Germany
Phone +49 7158 173-0
Fax +49 7158 5010
balluff@balluff.de



www.balluff.com